

Properties of System Trajectories

- thus far, we've discussed when a solution will exist and what's required for uniqueness / completeness.
- suppose we want to know more? more as in trajectory behavior?
 - how does the trajectory vary as components of the IVP vary?
 - if system dynamics depend on parameters, what happens when they vary?

* The focus of what's next is on analytical properties of system trajectories.

but first, an important Lemma!

Lemma (Gronwall-Bellman Inequality)

Let $\phi: [t_0, t_1] \rightarrow \mathbb{R}$ be cts and $\psi: [t_0, t_1] \rightarrow \mathbb{R}$ be cts and non-negative.

If a cts function $y: [t_0, t_1] \rightarrow \mathbb{R}$ satisfies

$$y(t) \leq \phi(t) + \int_{t_0}^t \psi(\tau) y(\tau) d\tau \quad \forall t \in [t_0, t_1]$$

then

$$y(t) \leq \phi(t) + \int_{t_0}^t \exp\left[\int_{\tau}^t \psi(\sigma) d\sigma\right] \phi(\tau) \psi(\tau) d\tau \quad \forall t \in [t_0, t_1].$$

If $\phi(t) = \phi_0$ constant, then

$$y(t) \leq \phi_0 \exp\left[\int_{t_0}^t \psi(\tau) d\tau\right]$$

and if it also holds that $\psi(t) = \psi_0$ constant, then

$$y(t) \leq \phi_0 \exp[\psi_0(t - t_0)].$$

proof.

we have $y(t) \leq \phi(t) + \underbrace{\int_{t_0}^t \psi(\tau) y(\tau) d\tau}_{(*)}$

let $z(t) \equiv \int_{t_0}^t \psi(\tau) y(\tau) d\tau$

and $v(t) \equiv z(t) + \phi(t) - y(t) \geq 0$

↑ holds by (*)

differentiating $z(t)$ w/ respect to t ,

$$\begin{aligned} \dot{z}(t) &= \psi(t) y(t) = \psi(t) (z(t) + \phi(t) - v(t)) \\ &= \psi(t) z(t) + \psi(t) [\phi(t) - v(t)] \end{aligned}$$

⇒ integrate

$$z(t) = \Phi_{t_0, t} \cdot z_0 + \int_{t_0}^t \Phi_{\tau, t} \psi(\tau) [\phi(\tau) - v(\tau)] d\tau,$$

where

$$\Phi_{t_0, t} = \exp\left[\int_{t_0}^t \psi(\tau) d\tau\right]$$

⇒ but, by definition of $z(t)$, $z(t_0) = 0$, so $z_0 = 0$

$$z(t) = \int_{t_0}^t \Phi_{\tau, t} \psi(\tau) [\phi(\tau) - v(\tau)] d\tau$$

but since $v(\tau) \geq 0$ and $\psi(\tau)$ is non-negative, we know that

$$z(t) = \int_{t_0}^t \Phi_{\tau, t} \psi(\tau) [\phi(\tau) - v(\tau)] d\tau \leq \int_{t_0}^t \Phi_{\tau, t} \psi(\tau) \phi(\tau) d\tau$$

↑ this part removed, since it evaluates to a positive number and therefore subtracts from the first term due to the minus sign.

⇒

$$z(t) \leq \int_{t_0}^t \exp\left[\int_{\tau}^t \psi(\sigma) d\sigma\right] \cdot \psi(\tau) \phi(\tau) d\tau$$

⇒ Now,

$$y(t) \leq \phi(t) + z(t)$$

⇒

$$y(t) \leq \phi(t) + \int_{t_0}^t \exp\left[\int_{\tau}^t \psi(\sigma) d\sigma\right] \psi(\tau) \phi(\tau) d\tau .$$

Now, if $\phi(t) = \phi_0$, then substitution and integration leads to

$$y(t) \leq \phi_0 \exp\left[\int_{t_0}^t \psi(\sigma) d\sigma\right]$$

and if $\psi(t) = \psi_0$ also, then

$$y(t) \leq \phi_0 \exp[\psi_0(t - t_0)].$$

- The Gronwall-Bellman inequality is immensely useful in providing explicit bounds for implicit inequalities.
(implicitly bounded quantities)
- Comes up very often in the study of dynamical systems.

Theorem (Continuous Dependence of System Trajectories on Time).

Let $f(x,t)$ be piecewise cts in t and ^{uniformly} Lipschitz cts in x and uniformly in t on $D \times [t_0, t_1]$. Then the solution $x(t; x_0, t_0)$ to the IVP is cts with respect to t_0 .

proof.

Suppose we had two IVP's, one with initial time t_0 and the other with $t'_0 > t_0$, then we can get continuity by showing that

$$\|x(t; x_0, t_0) - x(t; x_0, t'_0)\| \leq M(t'_0 - t_0) \exp(L(t - t'_0))$$

\uparrow
1st solution
 \uparrow
2nd solution
 \uparrow
going to be Lipschitz const.

for some $M > 0$, where both solutions exist on the interval $[t_0, t_1]$.

To see this, examine the two solutions for $t \in [t_0, t_1]$

$$x(t; x_0, t_0) = x_0 + \int_{t_0}^t f(x(\tau; x_0, t_0), \tau) d\tau$$

$$x(t; x_0, t'_0) = x_0 + \int_{t_0}^t f(x(\tau; x_0, t'_0), \tau) d\tau$$

\Rightarrow

$$\|x(t; x_0, t_0) - x(t; x_0, t'_0)\| = \left\| \int_{t_0}^{t'_0} f(x(\tau; x_0, t_0), \tau) d\tau + \int_{t'_0}^t [f(x(\tau; x_0, t_0), \tau) - f(x(\tau; x_0, t'_0), \tau)] d\tau \right\|$$

\Rightarrow TRIANGLE INEQUALITY

$$\leq \left\| \int_{t_0}^{t'_0} f(x(\tau; x_0, t_0), \tau) d\tau \right\| + \left\| \int_{t'_0}^t [f(x(\tau; x_0, t_0), \tau) - f(x(\tau; x_0, t'_0), \tau)] d\tau \right\|$$

$\Rightarrow \| \int f \| \leq \int \| f \|$

$$\leq \int_{t_0}^{t'_0} \| f(x(\tau; x_0, t_0), \tau) \| d\tau + \int_{t'_0}^t \| f(x(\tau; x_0, t_0), \tau) - f(x(\tau; x_0, t'_0), \tau) \| d\tau$$

now, f has the properties that allow one to assert that $\exists M > 0$ such that

$$\|f(x(t; x_0, t_0), t)\| \leq M \quad \text{on the finite time interval } [t_0, t_1].$$

\Rightarrow

$$\|x(t; x_0, t_0) - x(t; x_0, t'_0)\| \leq \int_{t_0}^{t'_0} M d\tau + \int_{t'_0}^t \|f(x(\tau; x_0, t_0), \tau) - f(x(\tau; x_0, t'_0), \tau)\| d\tau$$

furthermore, since f is ^{uniformly} Lipschitz cts in x uniformly in t , we can assert that $\exists L > 0$ such that

$$\|f(x(\tau; x_0, t_0), \tau) - f(x(\tau; x_0, t'_0), \tau)\| \leq L \|x(\tau; x_0, t_0) - x(\tau; x_0, t'_0)\|$$

\Rightarrow

$$\|x(t; x_0, t_0) - x(t; x_0, t'_0)\| \leq \int_{t_0}^{t'_0} M d\tau + \int_{t'_0}^t L \|x(\tau; x_0, t_0) - x(\tau; x_0, t'_0)\| d\tau$$

$$\underbrace{\|x(t; x_0, t_0) - x(t; x_0, t'_0)\|}_{y(t)} \leq \underbrace{M(t'_0 - t_0)}_{\phi_0} + \int_{t'_0}^t \underbrace{L \|x(\tau; x_0, t_0) - x(\tau; x_0, t'_0)\|}_{y(\tau)} d\tau$$

\Rightarrow invoke Gronwall-Bellman Lemma

$$\|x(t; x_0, t_0) - x(t; x_0, t'_0)\| \leq \phi_0 \exp[\gamma_0(t - t'_0)] = M(t'_0 - t_0) \exp[L(t - t'_0)].$$

To get continuity, notice that on the finite interval $[t_0, t_1]$, for all $\epsilon > 0$, if we

define $\delta(\epsilon) \equiv \frac{\epsilon}{M \exp[L(t - t'_0)]}$, then

$$|t'_0 - t_0| \leq \delta \quad \text{implies} \quad \|x(t; x_0, t_0) - x(t; x_0, t'_0)\| \leq \epsilon.$$

Theorem (Bounded Perturbations of the State Dynamics)

Let $f(x, t)$ be piecewise cts in t , uniformly Lipschitz cts in x , uniformly in t , on the domain $D \times [t_0, t_1]$ where D is an open, connected set.

Let $y(t)$ and $z(t)$ be solutions to the IVPs

$$\dot{y}(t) = f(y, t), \quad y(t_0) = y_0,$$

and

$$\dot{z}(t) = f(y, t) + g(y, t), \quad z(t_0) = z_0,$$

which lie in the set D over the time interval $[t_0, t_1]$. Suppose that g is uniformly bounded, e.g., $\exists \mu > 0$:

$$\|g(x, t)\| \leq \mu \quad \forall (x, t) \in D \times [t_0, t_1].$$

Then,

$$\|y(t) - z(t)\| \leq \|y_0 - z_0\| \exp[L(t - t_0)] + \frac{\mu}{L} (\exp[L(t - t_0)] - 1) \quad \forall t \in [t_0, t_1].$$

proof.

$$y(t) = y_0 + \int_{t_0}^t f(y(\tau), \tau) d\tau$$

$$z(t) = z_0 + \int_{t_0}^t [f(z(\tau), \tau) + g(z(\tau), \tau)] d\tau$$

\Rightarrow take norm of difference & use triangle inequality (twice)

$$\|y(t) - z(t)\| \leq \|y_0 - z_0\| + \left\| \int_{t_0}^t [f(y(\tau), \tau) - f(z(\tau), \tau)] d\tau \right\| + \left\| \int_{t_0}^t g(z(\tau), \tau) d\tau \right\|$$

$$\Rightarrow \| \int f \| \leq \int \| f \|$$

$$\leq \|y_0 - z_0\| + \int_{t_0}^t \|f(y(\tau), \tau) - f(z(\tau), \tau)\| d\tau + \int_{t_0}^t \|g(z(\tau), \tau)\| d\tau$$

$\Rightarrow g$ bounded

$$\leq \|y_0 - z_0\| + \int_{t_0}^t \mu d\tau + \int_{t_0}^t L \|y(\tau) - z(\tau)\| d\tau$$

\uparrow Lipschitz constant due to uniform Lipschitz continuity.

So, we are at

$$\|y(t) - z(t)\| \leq \|y_0 - z_0\| + \mu(t - t_0) + \int_{t_0}^t L \|y(\tau) - z(\tau)\| d\tau$$

$$\|y(t) - z(t)\| \leq \underbrace{\gamma}_{\zeta(t)} + \underbrace{\mu(t - t_0)}_{\phi(t)} + \int_{t_0}^t \underbrace{L}_{\psi(\tau)} \underbrace{\|y(\tau) - z(\tau)\|}_{\zeta(\tau)} d\tau$$

⇒ Gronwall-Bellman inequality

$$\|y(t) - z(t)\| \leq \gamma + \mu(t - t_0) + \int_{t_0}^t \exp[L(t - \tau)] \cdot (\gamma + \mu(\tau - t_0)) \cdot L d\tau$$

$$\leq \gamma + \mu(t - t_0) + \underbrace{\int_{t_0}^t \exp[L(t - \tau)] \gamma L d\tau}_{\text{integrate}} + \underbrace{\int_{t_0}^t \exp[L(t - \tau)] \cdot \mu(\tau - t_0) L d\tau}_{\text{integrate by parts}}$$

⇒

$$\leq \gamma \exp[L(t - t_0)] + \frac{\mu}{L} (\exp[L(t - t_0)] - 1)$$

⇒

$$\|y(t) - z(t)\| \leq \|y_0 - z_0\| \exp[L(t - t_0)] + \frac{\mu}{L} (\exp[L(t - t_0)] - 1)$$

□

MEANING : • a bounded perturbation gives rise to exponential divergence from the unperturbed system in the worst case.

(this is preferred to ~~blow-up~~ blow-up in finite time)

- therefore for finite time, the two solutions are a finite distance apart from each other. This could be useful.

Theorem (Continuous Dependence on Initial Conditions and Parameters)

Let $f(x, t; \lambda)$ be cts in (x, t, λ) , Lipschitz cts in x (uniformly in $\lambda \in \Lambda$) on the domain $D \times [t_0, t_1] \times \Lambda$, where D is open and connected and $\Lambda \equiv N(\lambda_0; c)$, for $c > 0$, is a neighborhood of λ_0 . Further, let $x(t; \lambda_0)$ be a solution to the IVP

$$\dot{x} = f(x, t; \lambda_0) \quad , \quad x(t_0; \lambda_0) = x_0 \in D$$

defined over the interval $[t_0, t_1]$ and lying in D for all $t \in [t_0, t_1]$.

Then $\forall \epsilon > 0, \exists \delta > 0$: if $\|z_0 - y_0\| < \delta$ and $\|\lambda - \lambda_0\| < \delta$,

there is a unique solution $z(t; \lambda)$ of the IVP

$$\dot{z} = f(z, t; \lambda) \quad , \quad z(t_0; \lambda) = z_0 \in D$$

defined on $[t_0, t_1]$ that satisfies

$$\|z(t, \lambda) - x(t, \lambda_0)\| < \epsilon \quad \forall t \in [t_0, t_1].$$

for proof see Hovakimyan lecture notes

or Khalil textbook

or most any other text covering dynamical systems theory.

Bounds on State Trajectories

- proof of continuity theorems for system trajectories utilized boundedness properties of the solution on finite time intervals.
- can we still find bounds if the time interval can be arbitrary?
 - ↳ yes, with a diff. eqn. version of the bounding theorems for series, integrals, etc.

idea is to use a known quantity to limit/bound an unknown quantity.

Lemma (Comparison Lemma). Consider the scalar differential equation

$$\dot{u} = g(u, t), \quad u(t_0) = u_0$$

where $g(u, t)$ is cts in t and Lipschitz cts in u on the domain $D \subset \mathbb{R}$ uniformly in $t \geq 0$. Let $[t_0, T)$ be the maximal interval of existence of the solution $u(t)$, and suppose that $u(t) \in D \forall t \in [t_0, T)$. Let $v(t)$ be a cts function whose upper right-hand derivative $D^+v(t)$ satisfies the differential inequality

$$D^+v(t) \leq g(v, t), \quad v(t_0) \leq u_0$$

with $v(t) \in D, \forall t \in [t_0, T)$. Then $v(t) \leq u(t)$.

Example.

$$\boxed{1} \quad \dot{x} = -(1+x^2)x \quad x(0) = a$$

→ what's going on w/ solution $x(t)$?

Well, suppose that $v(t) = x^2(t)$

⇒

$$\dot{v}(t) = 2x(t)\dot{x}(t) = -2x^2(t) - 2x^4(t) \leq -2x^2(t)$$

⇒

$$\dot{v}(t) \leq -2v(t)$$

pick $g(u,t) = -2u(t) \Rightarrow \dot{u}(t) = -2u(t)$

⇒

for $u(0) = x^2(0) = a^2$, $u(t) = a^2 e^{-2t}$

⇒

$$v(t) \leq u(t) \leq a^2 e^{-2t}$$

⇒

$$v(t) \leq a^2 e^{-2t}$$

How does this help?

well, since $v(t) = x^2(t)$

⇒

$$x^2(t) \leq a^2 e^{-2t}$$

⇒

$$|x(t)| \leq |a| e^{-t}$$

$x(t)$ is bounded by $|a|$.

2]

$$\dot{x} = -x + \frac{\sin(t)}{1+x^2} \quad x(0) = 2$$

Again, let $v(t) = \frac{1}{2} x^2(t)$

⇒

$$\dot{v}(t) = x(t) \dot{x}(t) = -x^2 + \frac{x \sin(t)}{1+x^2} \leq -x^2 + 1$$

⇒

$$\dot{v}(t) \leq -2v(t) + 1$$

Since $v(0) = \frac{1}{2} x^2(0) = 2$, we setup the companion IVP to be

$$\dot{u} = -2u + 1 \quad u(0) = 2$$

⇒ integrate to get solution

$$u(t) = \frac{1 + 3e^{-2t}}{2}$$

⇒

$$v(t) \leq u(t) = \frac{1 + 3e^{-2t}}{2}$$

⇒

$$|x(t)| = \sqrt{2v(t)} \leq \sqrt{1 + 3e^{-2t}}$$

- although we have no idea what happens to $x(t)$, we know that its absolute value is bounded.

